

THE NUMERICAL SOLUTION OF NONLINEAR DIFFERENTIAL EQUATIONS BY SPLINE FUNCTIONS

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1. Introduction

In this paper we are going to approximate the solution of the nonlinear differential equation

$$(1) \quad \begin{cases} y^{(m)}(x) = f[x, y(x), y'(x), \dots, y^{(m-1)}(x)], & x \in [0; 1], \\ y^{(j)}(0) = y_0^{(j)} \quad (j = 0, 1, \dots, m-1; m \geq 2) \end{cases}$$

supposing

$$(1.1) \quad f[x, y(x), y'(x), \dots, y^{(m-1)}(x)] \in C^{(r)}([0; 1])$$

where r is a fixed integer,

$$(1.2) \quad \left| f^{(q)}[x, y_1, y_1', y_1'', \dots, y_1^{(m-1)}] - f^{(q)}[x, y_2, y_2', y_2'', \dots, y_2^{(m-1)}] \right| \leq \\ \leq L \cdot \sum_{i=0}^{m-1} |y_1^{(i)} - y_2^{(i)}| \quad (q = 0, 1, \dots, r)$$

(Lipschitz condition), where

$$f^{(0)} = f, \quad f^{(q+1)} = f_x^{(q)} + f_y^{(q)} \cdot y' + f_{y'}^{(q)} \cdot y'' + \dots + f_{y^{(m-2)}}^{(q)} \cdot y^{(m-1)} + f_{y^{(m-1)}}^{(q)} \cdot f \\ (q = 0, 1, 2, \dots, r-1).$$

The problem of approximating the solution of nonlinear differential equations has been always of special interest. By spline functions the Cauchy problem $y' = f(x, y)$ was discussed by F. R. Loscalzo and T. D. Talbot [1], [2] and Th. Fawzy [3]. Some problems of a second order differential equation was solved by Gh. Micula [4], [5] by Th. Fawzy [6], [7] and by J. Györvári [8], [9], [10].

The main point of our method is that approximated values of $y^{(q)}(x_k)$ are constructed by the help of $y_0^{(j)}$ ($j = 0, 1, \dots, m-1$) and the function f , then using these approximate values $\bar{y}_k^{(q)}$ ($k = 0, 1, 2, \dots, n; q = 0, 1, 2$) the solution of (1) and its derivatives are approximated up to the $(m+r)$ -th order by the spline function of type $(0; 1; 2)$ defined in [6]. In the approximation theorems we use the average moduli defined in [11].

2. The first approximation process

2.1. Definition of the approximate values $\bar{y}_k^{(q)}$. Let

$$x_k = \frac{k}{n}; \quad h = \frac{1}{n}; \quad x_{k+1/2} = x_k + \frac{h}{2} \quad (k = 0, 1, \dots, n);$$

$$\omega(f^{(r)}, x, h) = \sup_{t_1, t_2 \in [x - \frac{h}{2}; x + \frac{h}{2}] \cap [0, 1]} |f^{(r)}(t_1) - f^{(r)}(t_2)|,$$

$$\tau(f^{(r)}, h) = \int_0^1 \omega(f^{(r)}, x, h) dx.$$

DEFINITION.

$$\begin{aligned} \bar{y}_0^{(j)} &:= y_0^{(j)} \quad (j = 0, 1, \dots, m-1), \\ \bar{y}_0^{(m+q)} &:= f^{(q)} [x_0, y_0, y_0', \dots, y_0^{(m-1)}] \quad (q = 0, 1, \dots, r), \\ \bar{y}_k^{(q)} &:= G_k^{(q)}(x_k) \quad (k = 1, 2, \dots, n-1; q = 0, 1, \dots, m+r), \\ \bar{y}_n^{(q)} &:= G_{n-1}^{(q)}(x_n) \quad (q = 0, 1, \dots, m+r), \end{aligned}$$

where

(2.1.1)

$$G_0(x) := \sum_{j=0}^{m-1} \frac{y_0^{(j)}}{j!} (x - x_0)^j + \sum_{q=0}^r \frac{f^{(q)} [x_0, y_0, y_0', \dots, y_0^{(m-1)}]}{(m+q)!} (x - x_0)^{m+q}$$

if $x_0 \leq x \leq x_1$;

(2.1.2)

$$\begin{aligned} G_k(x) &:= \sum_{j=0}^{m-1} \frac{G_{k-1}^{(j)}(x_k)}{j!} (x - x_k)^j + \\ &+ \sum_{q=0}^r \frac{f^{(q)} [x_k, G_{k-1}(x_k), G'_{k-1}(x_k), \dots, G_{k-1}^{(m-1)}(x_k)]}{(m+q)!} (x - x_k)^{m+q} \end{aligned}$$

if $x_k \leq x \leq x_{k+1}$ ($k = 1, 2, \dots, n-1$).

One can see that

$$G_{k-1}^{(j)}(x_k) = G_k^{(j)}(x_k) \quad (k = 1, 2, \dots, n-1; j = 0, 1, \dots, m-1).$$